



UIMU-HG1700-AG62

Economical, tactical grade IMU combines with SPAN GNSS+INS technology from Hexagon | NovAtel to deliver 3D position, velocity and attitude solution

World-leading GNSS+INS technology

SPAN GNSS+INS technology brings together two different but complementary technologies: Global Navigation Satellite System (GNSS) positioning and inertial navigation. The absolute accuracy of GNSS positioning and the stability of Inertial Measurement Unit (IMU) gyro and accelerometer measurements are deeply coupled to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when satellite signals are blocked.

UIMU-HG1700-AG62 overview

The UIMU-HG1700-AG62 contains a Honeywell HG1700-AG62 tactical grade IMU containing ring-laser gyros and servo accelerometers. The UIMU-HG1700 handles the power requirements of the IMU from a 12-28 VDC power input and provides the IMU data to a SPAN enabled GNSS+INS receiver such as the PwrPak7 using a custom NovAtel interface. IMU measurements are used by the GNSS+INS receiver to compute a blended GNSS+INS position, velocity and attitude solution at up to 100 Hz. The HG1700 is a commercial product that can be licensed under the jurisdiction of the U.S. Department of Commerce for customers outside the United States.

Advantages of UIMU-HG1700-AG62

Honeywell's high production volume of HG1700 IMUs enables excellent tactical grade performance for an economical price with short delivery times. The UIMU-HG1700-AG62 is available as a complete assembly including the IMU and environmentally sealed enclosure. For customers who already have the HG1700-AG62 IMU, the enclosure can be purchased separately and the IMU easily integrated.

Improve UMIU-HG1700-AG62 accuracy

Receivers from NovAtel provide your choice of accuracy and performance, from decimetre to RTK-level positioning. For more demanding applications, Waypoint Inertial Explorer post-processing software can be used to post-process real-time SPAN data on the UIMU-HG1700-AG68 and offers the highest level of accuracy with the system.



Benefits

- High performance IMU
- Optimal for aerial, hydrographic survey and industrial applications
- Easy integration with NovAtel's SPAN capable GNSS+INS receivers
- Rugged design ideal for challenging environments
- · High sensor dynamic range

Features

- Ring-laser gyros and servo accelerometers
- · Stationary INS alignment capable
- IMU data rate: 100 Hz
- SPAN GNSS+INS capability with configurable application profiles

SPAN System Performance¹

Horizontal Position Accuracy (RMS)

 Single point L1/L2
 1.2 m

 SBAS²
 60 cm

 DGPS
 40 cm

 TerraStar-L³.4
 40 cm

 TerraStar-C PRO³.4
 2.5 cm

 TerraStar-X³.4
 2 cm

 RTK
 1 cm + 1 ppm

Data Rate

IMU Raw Data Rate 100 Hz INS Solution Up to 200 Hz

Time Accuracy⁵ 20 ns RMS

Max Velocity⁶ 515 m/s

IMU Performance7

Gyro input range ±1000 deg/sec
Gyro rate bias 5.0 deg/hr
Gyro rate scale factor 150 ppm
Angular random walk 0.5 deg/√hr

Accelerometer range⁸ ±50 g
Accelerometer linearity 500 ppm
Accelerometer scale factor 300 ppm
Accelerometer bias 2.0 mg

Physical and Electrical

Dimensions 168 x 195 x 146 mm

Weight 4.5 kg

Power

Power consumption 8 W (typical) Input voltage +12 to +28 V

Connector MIL-C-38999-III, 22 pin

Environmental

Temperature

Operating $-30^{\circ}\text{C to } +60^{\circ}\text{C}$ Storage $-45^{\circ}\text{C to } +80^{\circ}\text{C}$

Humidity 95% non-condensing

MTBF 2,000 hrs

Waterproof IEC 60259 IPX7

Dust IEC 60259 IP6X

Compliance

FCC, ISED, CE

Optional Accessories

• Inertial Explorer post-processing software

Performance During GNSS Outages1

Outage Duration	Positioning Mode	Position Accuracy (M) RMS		Velocity Accuracy (M/S) RMS		Attitude Accuracy (Degrees) RMS		
		Horizontal	Vertical	Horizontal	Vertical	Roll	Pitch	Heading
0 s	RTK ⁹	0.02	0.03	0.015	0.010	0.010	0.010	0.025
	PPP	0.06	0.15					
	SP	1.00	0.60					
	Post-Processed ¹⁰	0.01	0.02	0.015	0.010	0.004	0.004	0.012
10 s	RTK ⁹	0.17	0.11	0.035	0.015	0.020	0.020	0.035
	PPP	0.21	0.23					
	SP	1.15	0.68					
	Post-Processed ¹⁰	0.01	0.02	0.020	0.010	0.004	0.004	0.013
60 s	RTK ⁹	4.02	0.53	0.165	0.025	0.035	0.035	0.060
	PPP	4.06	0.65					
	SP	5.00	1.10					
	Post-Processed ¹⁰	0.13	0.02	0.022	0.010	0.006	0.006	0.020

^{1.} Typical values (open sky conditions). Performance specifications subject to GNSS system characteristics, Signal-in-Space (SIS) operational degradation, ionospheric and tropospheric conditions, satellite geometry, baseline length, multipath effects and the presence of intentional or unintentional interference sources. 2. GPS-only. 3. Requires subscription to TerroStar data service. Subscriptions available from NovAtel. 4. TerroStar service available depends on the SPAIN enabled receiver yread. See the receiver product sheet for details. 5. Time accuracy does due to RF or antenna delay. 6. Export licensing restricts operation to a maximum of 515 metres/second. 7. Supplied by IMU manufacturer. 8. GNSS receiver sustains tracking up to 4 g. 9. 1 ppm should be added to all values to account for additional error due to baseline length. 10. Post-processing results using Inertial Explorer software.

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