SPAN™ SPAN-SE™



# Rugged GNSS/INS Receiver Delivers 3D Position, Velocity and Attitude Solution

# **Benefits**

Continuous, stable navigation

Supports IMUs from a variety of suppliers

Available as fully enclosed product or as board stack

Proven OEMV® technology

# **Features**

SD card data logging

GPS or GPS+GLONASS options

Single antenna and dual antenna support

Wheel sensor input for ground systems

Real time Heave filter for marine applications

# SPAN: World-Leading GNSS+INS Technology

SPAN (Synchronous Position, Attitude and Navigation) technology brings together two different, but complementary technologies: GNSS positioning and inertial navigation. The absolute accuracy of GNSS positioning and the stability of IMU gyro and accelerometer measurements are tightly coupled to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when satellite signals are blocked.

# **SPAN-SE Overview**

The SPAN-SE receiver enclosure provides the user interface to SPAN. It outputs raw measurement data or solution data over several communication protocols or to a removable SD card. Multiple GPS-synchronous strobes and event input lines offer easy integration into a larger system. Combining SPAN-SE with a SPAN-supported IMU creates a complete GNSS/INS system. For applications requiring an external heading reference, a dual antenna version of SPAN-SE is available.

# **SPAN-SE Advantages**

Tight coupling of the GPS and IMU measurements provides more satellite observations and the most accurate, continuous solution possible. Utilizing NovAtel's world-class GNSS receiver technology, the SPAN-SE delivers many powerful features including GPS+GLONASS capability and AdVance® RTK performance. A dedicated CPU for real-time GNSS/INS processing results in fast data rates and low raw data and solution latency for highly dynamic or time-critical applications.

# **Improve SPAN-SE Accuracy**

Take advantage of our Advance RTK as well as support for satellite-based augmentation systems such as OmniSTAR® or SBAS to improve real-time performance and accuracy. For more demanding applications, Inertial Explorer® (IE) post processing software from our Waypoint® product group can be used to post process SPAN-SE data and offers the highest level of accuracy with the system.

Dual Antenna option provides users with faster initial alignments in difficult low dynamics applications such as marine survey.

If you require more information about our SPAN products, visit novatel.com/products/span-gnss-inertial-systems



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1 cm+1 ppm

515 m/s

# SPAN-SE™

# SPAN System Performance<sup>1</sup>

Horizontal Position Accuracy (RMS)		
Single Point L1	1.5 m	
Single Point L1/L2	1.2 m	
SBAS	0.6 m	
CDGPS	0.6 m	
DGPS	0.4 m	
OmniSTAR		
VBS	0.6 m	
XP	0.15 m	
HP	0.1 m	
RT-20®	0.2 m	

#### **Measurement Precision**

L1 C/A Code	4 cm RMS
L1 Carrier Phase	0.5 mm RMS
	(differential channel)
L2 P(Y) Code	8 cm RMS
L2 Carrier Phase	1 mm RMS
	(differential channel)

#### Nata Rates

Maximum Velocity<sup>3</sup>

RT-2™

50 Hz
20 Hz
Up to 200 Hz
Up to 200 Hz
50 ns RMS

# **Physical and Electrical**

Dimensions	200 x 248 x 76 mm
Weight	3.4 kg
Power Consumption	_
Power Consumption	1

(single antenna) 10 W (typical) **Power Consumption** 

(dual antenna) 12 W (typical) Input Voltage +9 to +28 VDC

# **Antenna Port(s) Power Output**

+5 VDC **Output Voltage Maximum Current** 100 mA

#### **COM Port Output Power**

**Output Voltage** +9 to +30 VDC Maximum Current 1.5 A

#### **Connectors**

00111101	01010	
Power	ODU Mini Snap	o, Series K, 4 pin
I/0 1	ODU Mini Snap,	Series K, 30 pin
I/0 2	ODU Mini Snap,	Series K, 30 pin
Etherne	et	RJ-45
Primary	y RF	TNC Female
Second	lary RF	TNC Female
USB De	evice	Type B
USB Ho	st	Type A

### **Communication Ports**

RS232/RS422 software	
configurable UART COM Ports	4
IMU Connection	1
RTK correction	
Input UART COM Port	1
USB 2.0 Host	1
USB 2.0 Device	1
Ethernet	1
Removable SD Card	1
Event Input Triggers	4
Configurable Output Strobes	3

# **Environmental**

#### Temperature

Humidity	95% non-condensing
Storage	-50°C to +80°C
Operating	-40°C to +65°C

Waterproof IEC 60529 IPX7 IEC 60529 IP6X

#### Vibration (operating)

RTCA DO-160D, curve C Random Sinusoidal IEC 68-2-6 Shock (operating) IEC 68-2-27, 25 g

Dust

Emissions	FCC Part 15, Class B EN 55022, Class B
Immunity	EN 55024
Safety	EN 609050-1
MTRF	269 000 hrs

#### **Features**

- · Field-upgradable firmware
- Supports RTCM SC-104 version 3.0, CMR version 3.0, CMR+, NMEA 0183 version 3.01, and RTCA DO-217 message types

#### **Included Accessories**

- VDC power cable
- Two serial cables
- SD card
- · Mounting brackets
- CD
- USB 2.0 cable

# **Optional Accessories**

- · GPS-700 series antennas
- ANT series antennas
- RF cables 5, 10 and 30 m lengths
- Easy post-processing using Inertial **Explorer**

#### **Optional Dual Antenna**

ALIGN® Heading Accuracy

0.5 m Baseline  $0.40^{\circ}$ 1.0 m Baseline  $0.20^{\circ}$ 2.0 m Baseline 0.10°

# **Supported SPAN IMUs**

- UIMU-LCI
- UIMU-I N200
- UIMU-HG58/62
- IMU-FSAS
- IMU-CPT
- IMU-HG1900
- IMU-HG1930



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For the most recent details of this product: novatel.com/assets/Documents/Papers/SPAN-SE.pdf

- <sup>1</sup> GNSS/INS performance is dictated by the IMU integrated with SPAN.
- <sup>2</sup> Time accuracy does not include biases due to RF or antenna delay.
- <sup>3</sup> Export licensing restricts operation to a maximum of 515 metres per second.

