# SPAN-MPPCTM



# Power-PC Processer Board Stack Maximizes Navigation Capabilities in Challenging Environments

## **Benefits**

Continuous, stable navigation

Increased processing capability for demanding GNSS/INS applications

Supports IMUs from various suppliers

Small volume for size-restricted applications

## **Features**

**OEMV-3** form factor

Wheel sensor input for ground applications

Optional development kit

UART, USB, Ethernet and CAN peripherals

## **GNSS+INS Solution Unlike Any Others**

SPAN (Synchronous Position, Attitude and Navigation) technology brings together two different, but complementary technologies: GNSS positioning and inertial navigation. The absolute accuracy of GNSS positioning and the stability of inertial measurement unit (IMU) gyro and accelerometer measurements are tightly coupled to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when GNSS signals are blocked.

## **SPAN-MPPC Overview**

The SPAN-MPPC is designed to connect directly to NovAtel's OEMV-3 receiver to create a powerful GNSS/INS receiver board-stack. When connected to a SPAN-supported IMU, the MPPC creates a continuous GNSS/INS navigation system that delivers accurate position, velocity and attitude. It outputs raw measurement data or solution data over several communication protocols. Multiple GNSS-synchronous strobes and event input lines ensure the MPPC is easy to integrate into larger systems.

## **SPAN-MPPC Advantages**

Tight coupling of the GNSS and IMU measurements provides more satellite observations and the most accurate, continuous solution possible. With NovAtel's world-class OEMV® technology as its GNSS receiver, the SPAN-MPPC delivers many powerful features including GPS+GLONASS capability and AdVance® RTK performance. A dedicated CPU for real-time GNSS/INS processing results in fast data rates and low raw data and solution latency for highly dynamic or time-critical applications.

If you require more information about our SPAN products, visit novatel.com/products/span-gnss-inertial-systems



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## **SPAN-MPPC**

## SPAN System Performance<sup>1</sup>

**Horizontal Position Accuracy (RMS)** 

Single Point L1 Single Point L1/L2 1.5 m **SBAS** 0.6 m **CDGPS** 0.6 m **DGPS** 0.45 m OmniSTAR® 0.7 m **VBS** XΡ 0.15 m HP 0.1 m RT-20® 0.2 m RT-2™ 1 cm+1 ppm

#### **Measurement Precision**

L1 C/A Code 4 cm RMS
L1 Carrier Phase 0.5 mm RMS
(differential channel)
L2 P(Y) Code 8 cm RMS
L2 Carrier Phase 1 mm RMS
(differential channel)

#### **Data Rates**

GPS Measurement 50 Hz
GPS Position 20 Hz
IMU Measurement Up to 200 Hz
INS Solution Up to 200 Hz
Time Accuracy² 50 ns RMS
Maximum Velocity³ 515 m/s

## **Compatible IMUs**

IMU-H58 IMU-H62 IMU-LN200 IMU-FSAS

### **Physical and Electrical**

**Dimensions** 85 x 125 x 27<sup>4</sup> mm Weight 75 g

**Power** 

Power Consumption 8 W (typical with OEMV-3 connected) Input Voltage +9 to +30 VDC

Communication Ports
RS232/RS422 software
configurable UART Ports
IMU Connection
RTK correction Input UART COM Port
USB 2.0 Host
USB 2.0 Device
Ethernet
Event Input Triggers
Configurable Output Strobes

#### **Input/Output Connectors**

**OEMV-3 connections** 

1 x 40-pin dual row female connector

User connection

2 x 40-pin dual row connector

## **Environmental**

Temperature

Operating  $-40^{\circ}\text{C to } +85^{\circ}\text{C}^{5}$ Storage  $-50^{\circ}\text{C to } +85^{\circ}\text{C}$ 

**Humidity** 95% non-condensing

**Vibration (operating)** 

Random RTCA DO-160D, curve C Sinusoidal SAE J1211, 4g

**Shock (operating)** MIL-STD-810F method 516.5, 22g

Regulatory

4

1

1

1

1

4

3

Emissions FCC Part 15, Class B EN 55022, Class B

Immunity EN 55024

#### **Features**

- · Field-upgradable firmware
- Supports RTCM SC-104 version 3.0, CMR version 3.0, CMR+, NMEA 0183 version 3.01, and RTCA D0-217 message types

## **Included Accessories**

- · Mounting standoffs
- CD

#### **Optional Accessories**

- OEMV-3 receiver
- GPS-700 series antennas
- · ANT series antennas
- RF cables 5, 10 and 30 m lengths
- Heatsink



Version 2 -Specifications subject to change without notice

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For the most recent details of this product: novatel.com/assets/Documents/Papers/SPAN-MPPC. pdf

- Attitude performance is dictated by the IMU GNSS.
- <sup>2</sup> Time accuracy does not include biases due to RF or antenna delay.
- $^{\rm 3}$  Export licensing restricts operation to a maximum of 515 metres per second.
- <sup>4</sup> With OEMV-3 receiver.
- $^{\scriptscriptstyle 5}$  With heatsink.-40°C to +70°C without heatsink

