



OEM-IMU-HG4930

Small, affordable MEMS IMU combines with SPAN GNSS+INS technology from Hexagon | NovAtel to provide 3D position, velocity and attitude



World-leading GNSS+INS technology

SPAN GNSS+INS technology brings together two different but complementary technologies: Global Navigation Satellite System (GNSS) positioning and Inertial Navigation Systems (INS). The absolute accuracy of GNSS positioning and the stability of Inertial Measurement Unit (IMU) gyro and accelerometer measurements combine to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when satellite signals are blocked.

Sophisticated, tactical grade MEMS performance

The OEM-IMU-HG4930 is a high performing Micro Electromechanical Systems (MEMs) IMU. Economical, robust and small, the low power OEM-IMU-HG4930 provides tactical grade performance for unmanned vehicles and commercial and/or military guidance applications. When integrated with SPAN GNSS+INS technology, this IMU is ideal for airborne, marine and ground applications that require accurate 3D position, velocity and attitude data in a compact package.

OEM-IMU-HG4930 advantages

The OEM-IMU-HG4930 is comprised entirely of commercial components, simplifying export processes for this IMU.

Improved accuracy

Receivers from NovAtel provide your choice of accuracy and performance, from decimetre to RTK-level positioning. For the most demanding applications, Waypoint Inertial Explorer post-processing software offers the highest level of accuracy.

Benefits

- High performance IMU
- Optimal for aerial, hydrographic survey and industrial applications
- Easy integration with SPAN capable GNSS+INS receivers from NovAtel
- · Commercially exportable
- Low 5 VDC power input

Features

- MEMS gyros and accelerometers
- · Small size, rugged and light weight
- IMU data rate: 100 Hz or 400 Hz
- Direct UART interface to OEM7 receivers
- SPAN GNSS+INS capability with configurable application profiles

IMU performance¹

Gyroscope performance

Technology MEMS

Dynamic range² 400 °/sec

Bias instability 0.45 °/hr

Angular random walk 0.06 °/√hr

Accelerometer performance

Technology MEMS
Dynamic range 20 g
Bias instability 0.075 mg
Velocity random walk 0.06 m/s√hr

Physical and electrical

Dimensions $64.8 \, \text{dia} \times 35.7 \, \text{h mm (max)}$ Weight $200 \, \text{g}$

Power

Input voltage +5 VDC
Power consumption <3 W (typical)

Communication interface Serial port (TTL)

Connection to receiver Receiver serial port

Data rate

IMU raw data rate 100 Hz or 400 Hz INS solution Up to 200 Hz

Environmental

Temperature

Operating $-40^{\circ}\text{C to } +71^{\circ}\text{C}$ Storage $-40^{\circ}\text{C to } +80^{\circ}\text{C}$

 $\label{eq:mandomVibe} \textbf{Random Vibe} \qquad \qquad \textbf{MIL-STD-810G(Ch1)},$

Method 514.7 (2.0g)

Performance during GNSS outages^{3,4,5}

Outage duration	Positioning mode	Position accuracy (m) RMS		Velocity accuracy (m/s) RMS		Attitude accuracy (degrees) RMS	
		Horizontal	Vertical	Horizontal	Vertical	Roll/Pitch	Heading
0 s	RTK ⁶	0.02	0.03	0.015	0.010	0.010	0.030
	TerraStar-C PRO PPP	0.025	0.05				
	Single point	1.00	0.60				
10 s	RTK ⁶	0.12	0.08	0.035	0.020	0.018	0.040
	TerraStar-C PRO PPP	0.12	0.10				
	Single point	1.10	0.65				
60 s	RTK ⁶	3.80	0.73	0.165	0.030	0.030	0.055
	TerraStar-C PRO PPP	3.80	0.75				
	Single point	4.80	1.30				
	RTK with Land profile and DMI	2.50	0.55	0.115	0.030	0.030	0.055
0 s	Post-Processed using Inertial Explorer	0.01	0.02	0.015	0.010	0.003	0.010
10 s		0.01	0.02	0.015	0.010	0.003	0.010
60 s		0.11	0.05	0.017	0.010	0.004	0.014

- 1. Supplied by IMU manufacturer.
- 2. Full performance to 325 %s.
- 3. Performance may be impacted in conditions with unmitigated vibration or significant temperature variations.
- 4. Performance with one antenna, no DMI, and default SPAN profile unless otherwise specified.
- 5. Typical. Based on mixed urban road vehicle dynamics and benign GNSS conditions.
- 6. 1ppm should be added to all values to account for additional error due to baseline length

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